Advanced Modular 2/4-Channel PID Temperature Controllers

TMH Series

INSTRUCTION MANUAL

TCD230056AE

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.



Visit Autonics website (www.autonics.com or QR code) for the latest information, Manuals, CAD files, certifications, software, etc. are available. The dimensions, specifications, certifications, etc. are subject to change without notice for product improvement. Certain models may be discontinued without notice.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
 Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use or store the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be

ilure to follow this instruction may result in explosion or fire

- 03. Install the device in panel to use.
- lure to follow this instruction may result in fire
- 04. Do not connect, repair, or inspect the unit while connected to a power source.
- 05. Check 'Connections' before wiring.
- 06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire

⚠ Caution Failure to follow instructions may result in injury or product damage

- 01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N·m for screw type.
- When connecting the sensor input and communication cable without dedicated $% \left(1\right) =\left(1\right) \left(1\right)$ cable, use AWG 24 to 12 cable for screwless type , use AWG 28 to 16 cable for screw type, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N·m
- ilure to follow this instruction may result in fire or malfunction due to contact failure. 02. Use the unit within the rated specifications.
- ilure to follow this instruction may result in fire or product damage
- 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the
- Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
- For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (CT) temperature sensor, use the designated compensation wire for
- \bullet The connection of this unit should be separated from the power line and high voltage line in order to prevent inductive noise.
- In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.
- The connection of this unit should be separated from the power line and high voltage line in order to prevent inductive noise.
- Do not apply excessive power when connecting or disconnecting the connectors of the
- Switch or circuit breaker should be installed nearby users for convenient control
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
 When changing the input sensor, turn off the power first before changing.
- After changing the input sensor, modify the value of the corresponding parameter.

 Power supply should be insulated and limited voltage/current or Class 2, SELV power supply
- Do not overlapping communication line and power line.
- Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise

- · Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the
- Mounting multiple devices in any way other than the specified mounting method may cause heat to build up inside, which will shorten their service life. If there is a possibility of the ambient temperature rising to a temperature above the specified temperature range, take steps, such as installing fans, to cool the device. Be sure that the cooling method in not cooling just the terminal block. If only the terminal block is cooled, measurement errors may occur.
- · Additional settings may be required if the firmware version is different between the connected modules.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying
- Do not wire to terminals which are not used.
- Install DIN rail vertically from the ground.This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude max 2.000 m - Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

T M H O - O O O - O

■ Control module

Module

- 2: Control 2 channels Control 4 channels
- **2** Option Input/Output
- 2: Alarm output 1/2 (Module: 2)
- 4: Alarm output 1/2/3/4 (Module: 2) N. None (Module: 4)
- O Power supply

Option module

Module

A: Analog input/output E: Digital input/Alarm output **2** Option Input/Output

4: Analog 1 to 4 (Module: A) 8: Digital input 1 to 8, Alarm output 1 to 8

8: CT input 1 to 8 (Module: CT)

- Module

O Power supply Output

Control output R: Relay output S: SSR drive output

6 Terminal type

1: Screwless

: Selectable current or SSR drive output

- A: Transmission output
- R: Relay output N: None
- Terminal type
- None: Screv
- L: Screwless

■ Communication module

- 2 Option Input/Output
- ion output COM1+ COM2 O Power supply

4 Communication

- E: Ethernet : PLC Ladderless Terminal type
- None: Screw L: Screwless

Software

Download the installation file and the manuals from the Autonics website.

DAOMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Errors

■ Indicator

Name	Status	Color	Description	Troubleshooting		
PWR	ON	Red	☐ channel error: Input < Input range, Input > Input range,	When the error factor is resolved, it automatically		
CH□	Flash ⁰¹⁾	Red	Input sensor is open or not connected	returns to normal operation.		

■ Communication output, DAQMaster

Communication output (decimal)	DAQMaster	Description	Troubleshooting		
'31000'	Display 'OPEN'	Input sensor is open or not connected	When the error factor is resolved, it automatically returns to normal operation.		
'30000'	Display 'HHHH' 01)	Input > Input range			
'-30000'	Display 'LLLL' 01)	Input < Input range	retains to normal operations		
'31500'	Display '31500'	Sensor internal communication error	Check the power supply (24VDC==). (22)		

- 01) When HHHH / LLLL error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type. Please be careful.
- 02) This error may occur when connecting only the loader port

Product Components

Product (+ bracket)

· Instruction manual Module lock connector × 2

• Expansion connector \times 1 • [Screwless type] 5-pin connector \times 4

Sold Separately

- Current transformer (CT)
- CT connector cable: CICT4-
- Communication Converters: SCM-USP / SCM-38I / SCM-US48I / SCM-WF48
- Terminal Protection Cover: TMH-COVER

Specifications

■ Control module

Model	TMH2-DDD TMH2-DDD-L	TMH4-□□□ TMH4-□□□-L						
No. of channels	2 channels	4 channels						
Sampling period	50 ms (2 channels or 4 channels syn							
Input specification								
input specification	Thermocouple, RTD, Analog (refer to							
CT input	0.0 - 50.0A (primary current measu CT ratio: 1/1,000, • Measurement a							
	Connect input	Luracy: ±5% F.S. ±1 digit						
	ON: $\leq 1 \text{ k}\Omega$, OFF: $\geq 100 \text{ k}\Omega$							
	• Solid state input							
Digital input	Residual voltage: ≤ 0.9 V,	=						
	Leakage current: ≤ 0.5 mA							
	• Outflow current: ≈ 0.3 mA per inp	ut						
Control type	Heating, cooling, heating & cooling:	ON/OFF, P, PI, PD, PID control						
	• Relay: 250 VAC ~ 3 A 1a							
	mechanical life cycle: ≥ 10,000,00							
Control output	electrical life cycle: ≥ 100,000 ope	rations						
	• SSR: 12 VDC== $\pm 3 \text{ V}$, $\leq 20 \text{ mA}$							
	 Current ⁰¹⁾: DC 4 - 20 mA or DC 0 - 20) mA (Load: ≤ 500 Ω)						
	250 VAC∼ 3 A 1a							
	Mechanical life cycle: ≥ 10,000,000							
Alarm output	operations	-						
	Electrical life cycle: ≥ 100,000 operations							
Communication	Modbus RTU							
Communication	Thermocouple / RTD: 1 to 100 (0.1)	to 100.0\ °C /°E						
Hysteresis	• Analog: 1 to 100 digit	10 100.0) C/ F						
Proportional band	• Thermocouple / RTD: 0.1 to 999.9	C/°F						
(P)	• Analog: 0.1 to 999.9 %	C) I						
Integral time (I)	0 to 9.999 sec							
Derivative time (D)	0 to 9,999 sec							
C	Relay output, SSR drive output: 0.1	to 120.0 sec						
Control period (T)	Selectable current or SSR drive out							
Manual reset	0 to 100 (0.0 to 100.0) %							
Inculation time	Double insulation or reinforced insu	llation (mark: 🗉, dielectric strength						
Insulation type	between the measuring input part a	and the power part: 1 kV)						
Unit weight	≈ 174 g ≈ 162 g	≈ 154 g ≈ 151 g						
(packaged)	(≈ 249 g) (≈ 261 g)	(≈ 229 g) (≈ 250 g)						
01) When the control output	is set to the current output, the heater breal	k alarm function is not available.						

Option module

Model	TMHA-42A		TMHA-42A-L			
No. of channels	4 channels					
Sampling period	50 ms (4 channels	synchronous samp	ling)			
Input specification	Thermocouple, RTD, analog (refer to 'Input Specification')					
Transmission output	DC 4 - 20 mA or DC	0 - 20 mA (Load: ≤	500 Ω)			
Communication	Modbus RTU					
Insulation type		or reinforced insula uring input part and				
Unit weight (packaged)	≈ 160 g (≈ 235 g)		≈ 148 g (≈ 247 g)			
Model	TMHE-82R	TMHE-82R-L	TMHCT-82N	TMHCT-82N-L		
No. of I/O points	8 points		8 points			
Input specification	- Digital input • Connect input ON: ≤ 1 kΩ, OFF: • Solid state input Residual voltage: Leakage current: • Outflow current:	≤ 0.9 V,	- CT input • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 • Measurement accuracy: ±5% F.S. ±1 digit			
Alarm output	250 VAC∼ 3 A 1a, • Mechanical life cy ≤ 10,000,000 ope • Electrical life cycle ≤ 100,000 operat	erations e:	-			
Communication	Modbus RTU					
Insulation type	Double insulation or reinforced insulation (mark: ①, dielectric strength between the measuring input part and the power part: 1 kV)					
Unit weight (packaged)	≈ 163 g (≈ 239 g)	≈ 151 g (≈ 250 g)	≈ 144 g (≈ 219 g)	≈ 133 g (≈ 232 g)		

■ Communication module

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Model		TMHC-22L	TMHC-22L-L	TMHC-22E
Communi	• Connection type: RS422 / RS485 • Protocol: Modbus RTU,	Connection type: Ethernet		
-cation	COM2	PLC Lad	lderless	• Protocol: Modbus TCP
Insulation	type			tion (mark: 回, dielectric strength d the power part: 1 kV)
Unit weigh (packaged		≈ 147 g (≈ 222 g)	≈ 137 g (≈ 236 g)	≈ 129 g (≈ 204 g)

Common

Power supply	24 VDC==
Permissible voltage range	90 to 110% of rated voltage
Power Consumption	≤ 5 W (for max. load)
Display type	None- parameter setting and monitoring is available at external devices
Memory retention	pprox 10 years (non-volatile semiconductor memory type)
Insulation resistance	100 MΩ (500 VDC== megger)
Dielectric strength	Between the charging part and the case: 1,000 VAC $\sim 50/60~{\rm Hz}$ for 1 min
Vibration	0.75mm amplitude at frequency of 5 to 55Hz in each X, Y, Z direction for 2 hours
Noise immunity	Square shaped noise by noise simulator (pulse width 1 μ s) \pm 0.5 kV
Ambient temperature	-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)
Ambient humidity	35 to 85%RH, Storage: 35 to 85%RH (no freezing or condensation)
Protection structure	IP20 (IEC standard)
Certification	(€ 5½ ° 27 ™ №

Input Specifications

■ Input type and range

The setting range of some parameters is limited when using the decimal point display.

Input type		Decimal point	Display Method	Input rai	nge	(°C)	Input ra	ange	e (°F)
	K (CA)	1	K (CA) .H	-200	to	1,350	-328	to	2,462
	IN (CA)	0.1	K (CA) .L	-200.0	to	1,350.0	-328.0	to	2462.0
	J (IC)	1	J (IC) .H	-200	to	800	-328	to	1,472
	J (IC)	0.1	J (IC) .L	-200.0	to	800.0	-328.0	to	1472.0
	E (CR)	1	E (CR) .H	-200	to	800	-328	to	1,472
	E (CR)	0.1	E (CR) .L	-200.0	to	800.0	-328.0	to	1,472.0
	T (CC)	1	T (CC) .H	-200	to	400	-328	to	752
	T (CC)	0.1	T (CC) .L	-200.0	to	400.0	-328.0	to	752.0
Thermo	B (PR)	1	B (PR)	0	to	1,800	32	to	3,272
-couple	R (PR)	1	R (PR)	0	to	1,750	32	to	3,182
-couple	S (PR)	1	S (PR)	0	to	1,750	32	to	3,182
	N (NN)	1	N (NN)	-200	to	1,300	-328	to	2,372
	C (TT)	1	C (TT)	0	to	2,300	32	to	4,172
	G (TT)	1	G (TT)	0	to	2,300	32	to	4,172
	L (IC)	1	L (IC) .H	-200	to	900	-328	to 1,652	
	L (IC)	0.1	L (IC) .L	-200.0	to	900.0	-328.0	to	1,652.0
	U (CC)	1	U (CC) .H	-200	to	400	-328	to	752
	0 (CC)	0.1	U (CC) .L	-200.0	to	400.0	-328.0	to	752.0
	Platinel II	1	PLII	0	to	1,390	32	to	2,534
	Cu50 Ω	0.1	CU 50	-200.0	to	200.0	-328.0	to	392.0
	Cu100 Ω	0.1	CU 100	-200.0	to	200.0	-328.0	to	392.0
	JPt100 Ω	1	JPt100.H	-200	to	650	-328	to	1,202
RTD	JP1100 12	0.1	JPt100.L	-200.0	to	650.0	-328.0	to	1,202.0
KID	DPt50 Ω	0.1	DPt50.L	-200.0	to	600.0	-328.0	to	1,112.0
	DPt100 Ω	1	DPt100.H	-200	to	650	-328	to	1,202
	DELIOO 12	0.1	DPt100.L	-200.0	to	650.0	-328.0	to	1,202.0
	Nickel120 Ω	1	NI12	-80	to	260	-112	to	500
	0 to 10 V	-	AV1			0 to	10 V		
	0 to 5 V	-	AV2			0 to	5 V		
A I	1 to 5 V	-	AV3			1 to	5 V		
Analog	0 to 100 mV	-	AMV1			0 to	100 mV		
	0 to 20 mA	~	AMA1			0 to	20 mA		
	4 to 20 mA	-	AMA2			4 to	20 mA		

■ Measurement accuracy

Input type	temperature	type	Measurement accuracy
	At room	Screw	$ \begin{array}{l} (\text{PV}\pm 0.3\% \text{ or }\pm 1^{\circ}\text{C higher one})\pm 1\text{-digit} \\ \bullet \text{ Thermocouple K, J, T, N, E below -}100^{\circ}\text{C and L, U, PLII, RTD Cu50}\Omega, \text{DPt50}\Omega; \\ (\text{PV}\pm 0.3\% \text{ or }\pm 2^{\circ}\text{C higher one})\pm 1\text{-digit} \\ \bullet \text{Thermocouple C, G and R, S below 200^{\circ}\text{C}}; \\ (\text{PV}\pm 0.3\% \text{ or }\pm 3^{\circ}\text{C higher one})\pm 1\text{-digit} \\ \bullet \text{Thermocouple B below }400^{\circ}\text{C}; \text{there is no accuracy standards} \\ \end{array} $
Thermo -couple RTD	temperature (23 ±5 °C)	Screwless	$ \begin{array}{l} (\text{PV}\pm 0.5\% \text{ or } \pm 1^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{ Thermocouple K, J, T, N, E below -}100^{\circ}\text{C and L,} \\ \text{U, PLII, RTD Cu50}\Omega, \text{DPt50}\Omega; \\ (\text{PV}\pm 0.5\% \text{ or } \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit}} \\ \bullet \text{Thermocouple C, G and R, S below 200}^{\circ}\text{C}; \\ (\text{PV}\pm 0.5\% \text{ or } \pm 3^{\circ}\text{C higher one}) \pm 1\text{-digit}} \\ \bullet \text{Thermocouple B below } 400^{\circ}\text{C}; \text{there is no accuracy standards} \\ \end{array} $
	Out of room ten	nperature range	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or } \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{RTD Cu50} \ \Omega, \ \text{DPt50} \ \Omega: \\ (\text{PV}\pm0.5\% \text{ or } \pm 3^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Thermocouple R, S, B, C, G:} \\ (\text{PV}\pm0.5\% \text{ or } \pm 5^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Other sensors:} \leq \pm 5^{\circ}\text{C } (\leq -100^{\circ}\text{C}) \end{array} $
Analog		ature (23 ±5 °C)	±0.3% F.S. ±1-digit
7110105	Out of room ten	nperature range	$\pm 0.5\%$ F.S. ± 1 -digit

nodule can vary measurement accuracy about $\pm 1^{\circ}$ C, regardless of the

connected module.

Communication Setting

■ Interface

Module	Control	Option	Communicatio	n
Series	TMH2/4	TMHA, TMHE, TMHCT	TMHC-22L	TMHC-22E
Protocol	Modbus RTU		Modbus RTU, PLC Ladderless communication	Modbus TCP
Comm. method	RS485		RS422, RS485	Ethernet (10/100BaseT)
PC loader	TTL (Protocol: Modbus RTU)			
Maximum connection	32 units (address: 01 to 32) • 16 units in case of connecting TMHC module (address: 01 to 16) (address: 01 to 16) (address: 01 to 16) (address: 01 to 16)			
Synchronization	Asynchronous			-
Connection method	Two-wire half duplex			-
Comm. effective range	≤ 800 m			-
Comm. speed	4,800 / 9,600 (default) / 19,20 (parameter)	00 / 38,400 / 1	.15,200 bps	10/100 Mbps
Response time	5 to 99 ms (default: 20 ms)			-
Start bit	1 bit (fixed)			-
Data bit	8 bit (fixed)			-
Parity bit	None (default) , Odd, Even			-
Stop bit	1 bit, 2 bit (default)			-
EEPROM life cycle	≈ 1,000,000 operations (Era	se / Write)		

 When changing the setting value related to communication interface, reboot the device for normal operation.
 It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication

Address

Set the communication address with the communication address setting switch (SW1, default: 1) and communication address group switch (SW2, default: +0, TMH2/4 Series).

	SW1								Ć	Ø.							
Series		0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
TMH2/4	+0 +16	16	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
IMITZ/4	+0 +16	32	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
TMHC		16	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
TMHA		48	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
TMHE		64	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63
TMHCT		80	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79

When connecting TMHC and TMH2/4 to master separately, communication address can be duplicated, but if they communicate with master at the same time, communication address must not be duplicated to avoid error. (use address TMHC: 1 to 16, TMH2/4: 17 to 32)

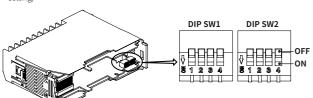
■ Mac address [Ethernet communication module]

It is possible to check Mac address for Ethernet communication at DAQMaster. Refer to the manual for the details.

■ DIP switch setting [Ladderless communication module]

After separating base terminal block, set communication speed, stop bit, PLC connection and protocol by using a internal DIP switch.

• Setting values are applied to COM1 only, default: All switches OFF (following parameter setting)



DIP SW1

1	2	Communication speed	3	4	Stop bit
OFF	OFF	Following parameter setting	OFF	OFF	Following parameter setting
OFF	ON	19,200 bps	OFF	ON	Stop bit: 1 bit
ON	OFF	38,400 bps	ON	OFF	Stop bit: 2 bit
ON	ON	115,200 bps	ON	ON	-

DIP SW2

1	2	3	4	PLC connection and protocol
OFF	OFF	OFF	OFF	Following parameter setting
OFF	OFF	OFF	ON	Modbus RTU
OFF	OFF	ON	OFF	LS MASTER-K Series special protocol
OFF	OFF	ON	ON	LS GLOFA-GM Series special protocol
OFF	ON	OFF	OFF	LS XGT/XGB Series special protocol
OFF	ON	OFF	ON	MITSUBISHI MELSEC Series special protocol Q/QnACPU common command (1401/0401)
OFF	ON	ON	OFF	MITSUBISHI MELSEC Series special protocol ACPU common command (WW/WR)
OFF	ON	ON	ON	OMRON SYSMAC Series special protocol
ON	OFF	OFF	OFF	MITSUBISHI MELSEC3 Series special protocol

Installation Method

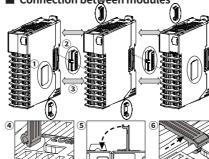
■ Separating base terminal block





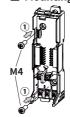
- 1 Push the lock lever at ①
- 2. Pull the body of the module to ② direction.
- When connecting base terminal block, align the upper concave part (□) of the body and the upper convex part (□) of the base, then lower it vertically to connect it. If the upper parts are not align correctly, it may damage to the inner connector.

■ Connection between modules



- 1. Remove END cover (1) of (except END cover of the first and last module).
- (2) Insert expansion connector (2) and connect them tightly to ③ direction (max. 31 units).
- Insert module lock connector (4) to lock connector hole (⑤).
- Push module lock connector to the lock direction (6).
- \bullet Supply power to the rear power terminal of only one of the connected modules. Supply adequate power for power input specifications and overall capacity. (Max. power when connecting 32 modules: $32 \times 5 W = 160 W$)

■ Mounting with bolts



- 1. Refer to 'Separating base terminal block' to separate base terminal
- 2. Install the module by using M4 screws to the $\ensuremath{\ensuremath{\textcircled{1}}}$ direction of the inside mounting hole.
- Refer to the 'Dimensions' to check hall positions and dimensions of inside mounting hole.

■ Mounting on DIN rail





- 1. Press the rail lock at the top / bottom of the module to the ① direction.
- . Hang the top rail lock to DIN rail.
- 3. Push to ② direction and press to ③ direction.

- Separation



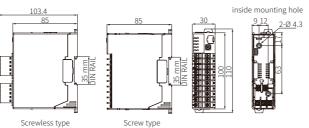
- Press the module to ① direction.
- Keep it pressed and pull it to ② direction.

Precautions

- Install the module vertically.
- · Use end plates (sold separately, not available from Autonics) to fix firmly.

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



Terminal

• Unit: mm, Use the terminal of follow shape.

■ Screw: Crimp terminal



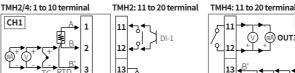
Fork crimp terminal Round crimp terminal

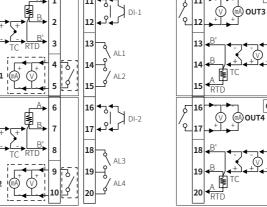
Connections

• Do not arbitrarily remove the terminal screws, and use them after fully tightening them. Failure to follow this instruction may result in malfunction due to contact failure.

■ Control module

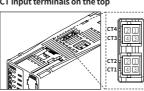
CH2

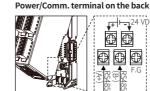




minal	Functio	n 1	Functio	n 2	Terminal				Functio	n1	Functio	n2
01.14		Α	-	_	11	Digital input 1	11	СНЗ	Relay,	E		
CH1 input	RTD	B	TC, current.	+	13	Alarm output 1		output	current, SSR	+	-	
		B'	voltage	L	14	Common	13	0110		B'	TC,	E
CH1	Relay, current.	+	-		15	Alarm output 2	14	CH3 input	RTD	В	current, voltage	+
output	SSR			_	16 17	Digital input 2	15			Α	-	
CH2		A B	TC.	_	18	Alarm output 3		CH4	Relay, current.	F	_	
input	RTD	B'	current,	Ť	19	Common	17	output	SSR	+		
		B.	voltage		20	Alarm output 4	18			B'	TC,	Ŀ
CHZ	Relay, current.	+	-				19	CH4 input	RTD	В	current, voltage	+
output	SSR	_		_			20			Α	-	

CT input terminals on the top





■ Screwless: Wire ferrule

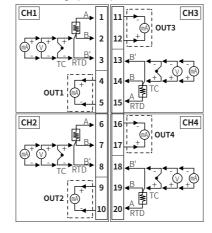
CH3

CT connector cable(CICT4-□, sold separately)

	Pin	Cable color	CT connection
	1	Brown	CT 2 / CT 4
3 4	2	Blue	CT 2 / CT 4
	3	White	CT1/CT3
	4	Black	CT 1 / CT 3

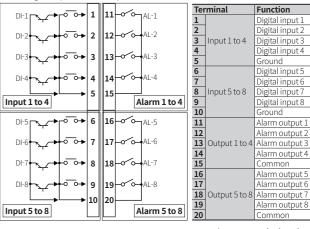
■ Option module

TMHA [Analog input / output]



r	minal	Functio	n 1	Function 2
	CH1 input	RTD	A B B'	- TC, current, + voltage –
	CH1 output	Current	+	-
	CH2 input	RTD	A B B'	TC, current, + voltage –
)	CH2 output	Current	+	-
	CH3 output	Current	+	-
	CH3 input	RTD	B' B A	TC, current, — voltage +
	CH4 output	Current	<u>-</u>	-
	CH4 input	RTD	B' B	TC, current, — voltage +

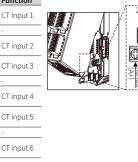
TMHE [Digital input / Alarm output]

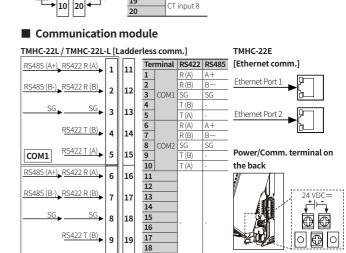


TMHCT [CT input]

COM2

Power/Comm. terminal on the back





CT input 7